Radu Alexandru Rosu

Personal Data

PLACE AND DATE OF BIRTH: Targoviste, Romania | 16 September 1992

CURRENT ADDRESS: Rheingasse 2, 53113, Bonn, Germany

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WORK EXPERIENCE

PRESENT

Researcher at University of Bonn

DEC 2018 | 3D Deep Learning

Developed neural networks capable of processing and understanding the 3D world. Researched novel semantic segmentation approaches suitable for raw point clouds or triangular meshes. Interested in models that can learn implicit neural representations and disentangled representations of the 3D world.

Oct 2016

Tutor at University of Bonn

Computer Vision

Tutor for the Computer Vision course, responsible for one of the exercise groups. Responsibilities included grading, assisting the students in their learning and answering questions regarding the topics presented in the lecture.

May 2015

Student research assistant at University of Bonn

Visual SLAM

Helped in developing fast and robust SLAM solutions for usage in MAVs (Micro Aerial Vehicles). Worked with both feature-based and direct SLAM approaches and in developing fast Bundle Adjustment methods using the Ceres Solver and g2o.

EDUCATION

PRESENT

PhD in 3D Deep Learning,

DEC 2018

Rheinische Friedrich-Wilhelms-Universität Bonn, Germany.

Ongoing as part of my research work in 3D deep learning.

SEP 2018

Master's Degree in Computer Science,

Rheinische Friedrich-Wilhelms-Universität Bonn, Germany.

Thesis: "Semi-Supervised Semantic Mapping through Label Propagation

with Semantic Texture Meshes"

Supervisor: Prof. Dr. Sven Behnke

JULY 2015

Bachelor's Degree in Computer Science,

University of Salamanca, Spain.

Project: "Reconstruction of 3D Figures from Computerized Tomography"

Supervisor: Prof. Iván Álvarez NAVIA

JULY 2014

Student Exchange Year (ERASMUS),

University of Wolverhampton, United Kingdom.

PUBLICATIONS (FIRST AUTHOR)

- LatticeNet: Fast Point Cloud Segmentation Using Permutohedral Lattices Radu Alexandru Rosu, Peer Schütt, Jan Quenzel, and Sven Behnke Robotics: Science and Systems (RSS), July 2020
- Reconstruction of Textured Meshes for Fire and Heat Source Detection Radu Alexandru Rosu, Jan Quenzel, and Sven Behnke Safety, Security, and Rescue Robotics (SSRR), September 2019
- Semi-Supervised Semantic Mapping through Label Propagation with Semantic Texture Meshes

Radu Alexandru Rosu, Jan Quenzel, and Sven Behnke International Journal of Computer Vision (IJCV), Springer, 2019

FURTHER PUBLICATIONS

 Beyond Photometric Consistency: Gradient-based Dissimilarity for Improving Visual Odometry and Stereo Matching

Jan Quenzel, Radu Alexandru Rosu, Thomas Läbe, Cyrill Stachniss, and Sven Behnke IEEE International Conference on Robotics and Automation (ICRA), Paris, France, May 2020

• Bonn Activity Maps: Dataset Description

Julian Tanke, Oh-Hun Kwon, Patrick Stotko, Radu Alexandru Rosu, Michael Weinmann, Hassan Errami, Sven Behnke, Maren Bennewitz, Reinhard Klein, Andreas Weber, Angela Yao, Juergen Gall

• Team NimbRo at MBZIRC 2017: Fast Landing on a Moving Target and Treasure Hunting with a Team of MAVs

Marius Beul, Matthias Nieuwenhuisen, Jan Quenzel, Radu Alexandru Rosu, Jannis Horn, Dmytro Pavlichenko, Sebastian Houben, and Sven Behnke Journal of Field Robotics (JFR), January 2019

- Online Depth Calibration for RGB-D Cameras using Visual SLAM
 Jan Quenzel, Radu Alexandru Rosu, Sebastian Houben, and Sven Behnke
 International Conference on Intelligent Robots and Systems (IROS), Vancouver, Canada, September 2017
- Collaborative Object Picking and Delivery with a Team of Micro Aerial Vehicles at MBZIRC

Matthias Nieuwenhuisen, Marius Beul, Radu Alexandru Rosu, Jan Quenzel, Dmytro Pavlichenko, Sebastian Houben, and Sven Behnke

European Conference on Mobile Robotics (ECMR), Paris, France, September 2017

COMPUTER SKILLS

Proficient Knowledge: C++, CUDA, PYTHON, HALIDE, PYTORCH, L'TEX

Intermediate Knowledge: Java, Scala, LINUX ADMINISTRATION

Miscellaneous: AUTODESK 3DS MAX, ZBRUSH

LANGUAGES

ROMANIAN: Mother tongue

ENGLISH: Fluent SPANISH: Fluent

GERMAN: Intermediate Knowledge (B1)

INTERESTS AND ACTIVITIES

Robotics, 3D Deep Learning, HPC, Artificial Intelligence Travelling and backpacking